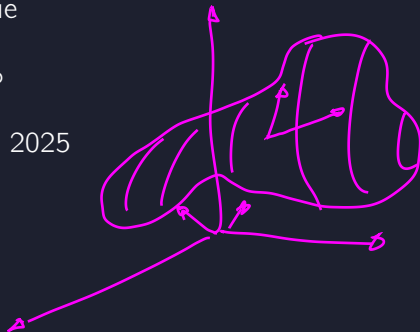


Manifolds

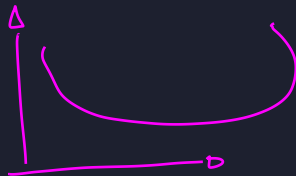
Jon Bosque

CMK Group

September 22, 2025



Manifolds



Manifold Representation

Implicit Manifolds

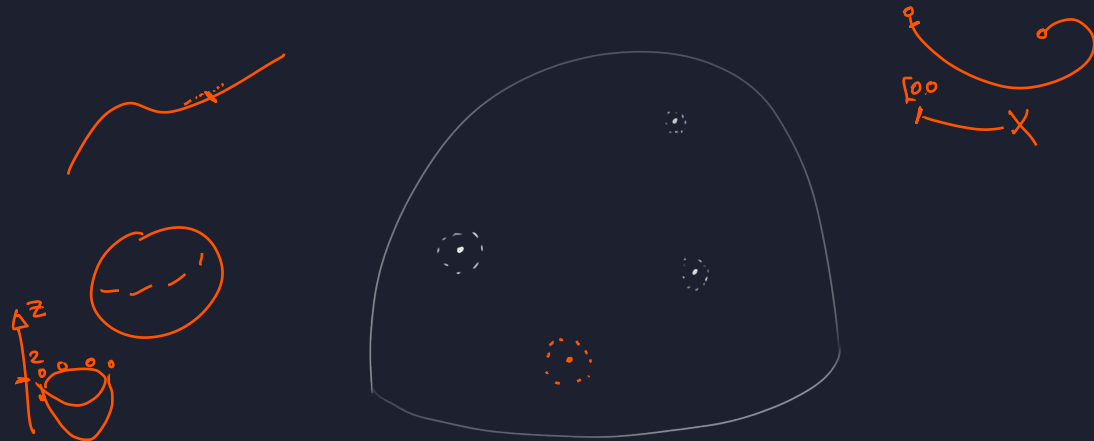
Parametric Manifolds

Abstract Manifolds \rightarrow

} Ambient Space

Manifolds

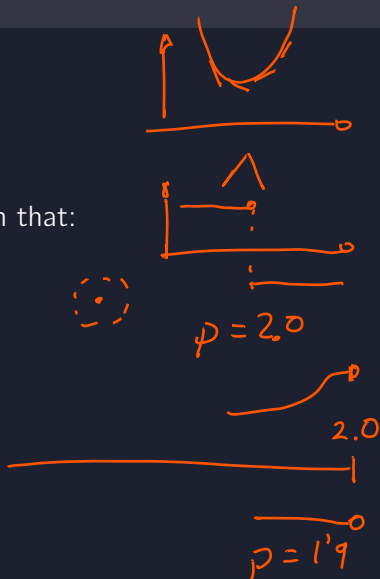
A k -dimensional manifold, M is any topological space that given any point in the manifold its neighborhood looks like a ball in \mathbb{R}^k



Topological Space

A topological space is a collection of subsets of X such that:

- ▶ \emptyset and X are open.
- ▶ Arbitrary unions of open sets are open.
- ▶ Finite intersections of open sets are open.



Maifold



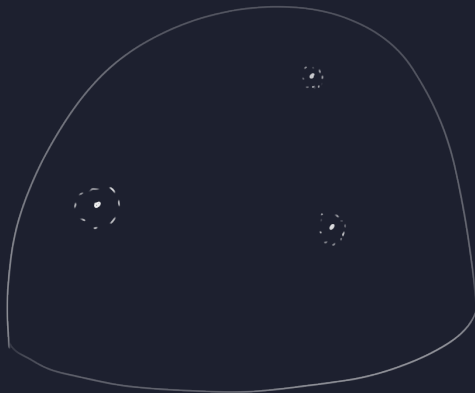
A Manifold is a topological space M that is:

- ▶ Hausdorff: For any two distinct points, there exist disjoint open sets containing each.
- ▶ Second-countable: There exists a countable basis for the topology.
- ▶ Locally Euclidean: Every point $x \in M$ has a neighborhood homeomorphic to an open subset of \mathbb{R}^n .




Manifolds

A k -dimensional manifold, M is any topological space that given any point in the manifold its neighborhood looks like a ball in \mathbb{R}^k



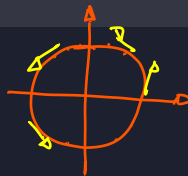
Implicit Representation

M is a k -dimensional manifold if $\forall p \in M$, $\exists U$ such that $p \in U$, and $(n - k)$ differentiable functions f_1, f_2, \dots, f_{n-k} such that

1. U is an open set
2. $M \cap U = (p_1 = 0) \cap \dots \cap (p_{n-k} = 0)$
3. $\forall p \in M \cap U$ the gradients ∇f_i are linearly independent $\forall i$  *Smooth*

The implicit representation of the circle

$$x^2 + y^2 = 1$$



$$S^1 = \{(x, y) : f = x^2 + y^2 - 1 = 0\}$$

The gradient is always linearly independent

$$\nabla f = \left(\frac{\delta f}{\delta x}, \frac{\delta f}{\delta y} \right) = (2x, 2y)$$

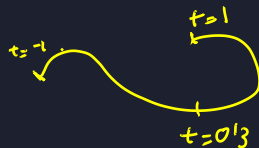
Parametric Representation

M is a k -dimensional manifold if $\forall p \in M$ there is an open set U in \mathbb{R}^k containing p and a parametrizing map ϕ such that

$$\phi(\text{Ball in } \mathbb{R}^k) = M \cap U$$

The parametric representation of the circle

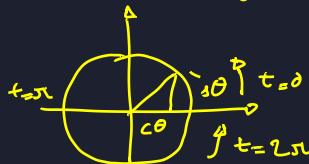
$$t: [-1, 1]$$



$$\varphi: (0, 2\pi) \rightarrow S^1 \subset \mathbb{R}^2$$

$$\varphi(\theta) = (\cos \theta, \sin \theta)$$

$$J_{\varphi}(\theta) = \begin{bmatrix} \frac{\partial}{\partial \theta} \cos \theta \\ \frac{\partial}{\partial \theta} \sin \theta \end{bmatrix} = \begin{bmatrix} -\sin \theta \\ \cos \theta \end{bmatrix}$$



Abstract Manifolds



M is an n -dimensional manifold if there is an open cover, where each U_α has an associated homeomorphism:

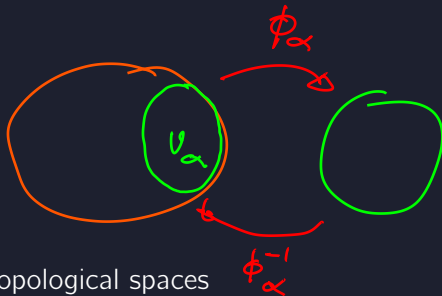
$$\phi_\alpha : U \rightarrow V$$

where $V \subset \mathbb{R}^n$

—
Homeomorphism, a function that is:

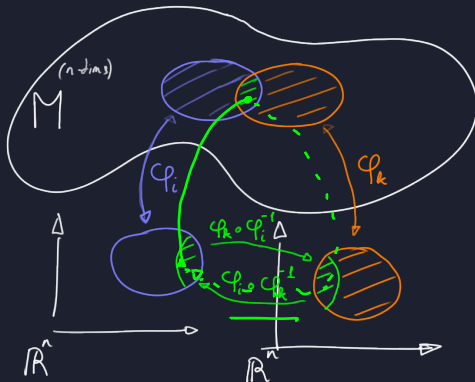
- ▶ continuous
- ▶ bijective
- ▶ with a continuous inverse

An homeomorphism is a 1-1 mapping between topological spaces



Abstract Manifolds

- ▶ The ϕ_α mappings are called **charts**
- ▶ A set of charts $\phi_i : U_\alpha \rightarrow V \mid i \in \mathbb{N}$ is called the **atlas** of M



This mapping allow us to do calculus on \mathbb{R}^n , where it is well defined

Stereographic Projection as an Atlas

Define two open sets covering S^1 :

► $U_+ = S^1 \setminus \{(0, 1)\}$ ←

► $U_- = S^1 \setminus \{(0, -1)\}$ ←



Charts:

$$\varphi_+ : U_+ \rightarrow \mathbb{R}$$

$$(x, y) \mapsto \frac{x}{(1 - y)}$$

Pole N

$$\varphi_- : U_- \rightarrow \mathbb{R}$$

$$(x, y) \mapsto \frac{x}{(1 + y)}$$

Pole S

Atlas:

$$(\{U_+, U_-\}, \{\varphi_+, \varphi_-\})$$

Stereographic Projection as an Atlas

